Although this program has been tested by the contributor, no warranty, express or implied, is made by the contributor, Digital Equipment Computer Users Society or Digital Equipment Corporation as to the accuracy or functioning of the program or related program material, and no responsibility is assumed by these parties in connection therewith.
ABSTRACT

This program is a focal version of the game LIFE attributed to John Horton Conway of the Cavendish Laboratory in Cambridge, England.

The computer plays with a matrix of locations, each of which may start as full or empty. Full locations are said to contain "cells", which live, multiply or die according to the following rules:

- Each location is bounded by eight neighboring locations, except at the edges of the matrix.
- Each cell with two or three neighboring cells will survive.
- Each cell on its own, or with only one neighbor, will die of isolation. Each cell with four or more neighbors will die of over-population.
- Each empty location with three or more cells neighboring it will be filled by a new cell.

This program starts after a GO command by asking the operator to specify the size of the matrix to be used. The maximum size on a 4K machine is 4 X 4, but an 8K machine permits the use of an 11 X 11 matrix. After this, the operator must specify the X and Y coordinates of cells in the starting position, specifying zero as a coordinate results in a typeout of the starting matrix, after which the computer asks if the next "generation" of cells should be plotted.

A sample printout with user's responses in angled < > brackets:

LIFE

Matrix size M'M ? M?: <11>

Type X + Y coordinates of occupied cells
Zero stops further entries
X:<4>  Y:<5>  X:<5>  Y:<5>  X:<6>  Y:<5>
X:<Ø>  Y:<Ø>
MATRIX IS

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Next generation?: <Yes>

MATRIX IS

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Next generation?: <Yes>

MATRIX IS

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Next generation?: <Yes>
The next generation was identical to the second one above. This attainment of a constant cycle of structures is a very common outcome of the game.

REFERENCES


2. Scientific American, October 1970

3. IBID, February 1971

4. IBID, April 1971

RESTRICTIONS

A 4K PDP-8 allows a matrix of only 4 X 4 or less, but 8K FOCAL allows the use of an 11 X 11 matrix.
C-8K FOCAL 91969

01.01 C; LIFE
01.02 T !!!,"LIFE"»,!
01.03 A "MATRIX SIZE M*? N ?",M
01.04 S MM=M*M;F J=1,1,MM;S C(J)=0
01.05 T !!!,"TYPE X & Y COORDINATES OF OCCUPIED CELLS"»,!
01.06 T "ZERO STOPS FURTHER ENTRIES"»,!
01.07 A "X"",X"",Y",Y
01.08 I (X)2,10,2,10;I (Y)2,10,2,10
01.09 I (M-X)1,30;I (N-Y)1,30;S J=(Y-1)*X+X;S C(J)=1;G 1,60
01.00 T !!!,"OUTSIDE MATRIX "",M","",M;C 1,60

02.10 T Z2,00;!,"MATRIX IS"»,!
02.11 F Y=1,1;MID 3
02.12 T !!!A "NEXT GENERATION?"»,J
02.13 I (J-0 YES)2,60,5,10,2,60
02.14 I (J-0 NO)2,70,2,50,2,70
02.15 T "ANSWER YES OR NO"»,!;C 2,0
02.16 Q

03.20 T !!!F X=1,1;M;D 4
03.21 R

04.20 S J=(Y-1)*M+X;I (C(J))4,30,4,30,4,40
04.22 T ":";R
04.23 T ":0";R

05.10 F Y=1,1;MID 6
05.20 F J=1,1;MX;D 10
05.30 C 2,10

06.23 F X=1,1;MID 7
06.30 R

07.10 S J=(Y-1)*M+X;S P=0
07.20 I (X-1)7,40,7,40;I (M-X)7,3,7,30
07.21 I (X-1)7,28,7,23;I (M-X)7,25,7,29
07.22 D 8,1;D 8,2;D 8,3;D 8,4;D 8,5;D 8,6;D 8,7;D 8,8;D 7,70
07.23 D 8,6;D 8,2;D 8,5;D 8,4;D 8,3;C 7,70
07.24 D 8,7;D 8,3;D 8,8;D 8,1;D 8,6;C 7,70
07.25 I (X-1)7,33,7,33;I (M-X)7,34,7,34
07.26 I (X-1)7,31,7,31;I (M-X)8,2;D 3,5;C 7,70
07.27 D 8,6;D 8,2;D 8,5;D 8,4;D 8,3;C 7,70
07.28 D 8,3;D 8,4;D 8,1;D 8,6;C 7,70
07.29 I (X-1)7,50,7,50;I (M-X)7,60,7,60
07.30 I (X-1)7,50,7,50;I (M-X)7,60,7,60
07.31 D 8,3;D 8,8
07.32 D 8,5;D 8,4;D 8,7;C 7,70
07.33 D 8,7;D 8,3;D 8,8
07.34 I (C(J))7,30,7,30,7,30
07.35 I (P-3)7,32;S C(J)=1;R
07.36 R
07.37 I (P-1)7,92,7,92;I (4-P)7,92,7,92;R
07.38 S C(J)=100
08:10 S TL=(J-1-M);I (C(TL))9.11,9.11,9.12
08:20 S TR=(J+1-M);I (C(TR))9.11,9.11,9.12
08:30 S BL=(J-1+X);I (C(BL))9.11,9.11,9.12
08:40 S BR=(J+1+M);I (C(BR))9.11,9.11,9.12
08:50 S R=J+1;I (C(R))9.11,9.11,9.12
09:00 S T=J-M;I (C(T))9.11,9.11,9.12
09:10 S B=J+M;I (C(B))9.11,9.11,9.12
09:20 S L=J-1;I (C(L))9.11,9.11,9.12

09:11 R
09:12 S P=P+1;R

10:10 I (C(J))10.43,10.60;I (C((J)-1))10.60,10.40,10.60
10:40 S C(J)=1;R
10:60 S C(J)=0;R

*99999999999999999999999999999999