

DECUS NO.	8-317
TITLE	EIG (Compute Eigenvalues and Eigenvectors)
AUTHOR	J. N. R. Jeffers
COMPANY	Submitted by: A. J. P. Gore The Nature Conservancy Lancashire, England
DATE	September 25, 1969
SOURCELANGUAGE	FORTRAN D

Although this program has been tested by the contributor, no warranty, express or implied, is made by the contributor, Digital Equipment Computer Users Society or Digital Equipment Corporation as to the accuracy or functioning of the program or related program material, and no responsibility is assumed by these parties in connection therewith.



EIG (Compute Eigenvalues and Eigenvectors)

DECUS Program Library Write-up

DECUS No. 8-317

ABSTRACT

The extraction of eigenvalues and eigenvectors is carried out by means of a group of programs, the intermediate stages of the computations being stored on the disk. The eigenvalues, and the associated eigenvectors, are extracted one by one, starting with the largest eigenvalue, and the process can be terminated as soon as sufficient eigenvalues have been extracted from the basic data matrix. The programs were designed to enable principal component and canonical variate analyses to be carried out.

TAPES REQUIRED

1. Form of program tapes - All program tapes are written in the PDP-8 FORTRAN-D language, and are in the source language. There are four programs in the set, as follows:

- (a) SMOD program to store data matrix on disk.
- (b) EIG1 program to compute the highest latent root and vector.
- (c) EIG2 program to extract and print the highest latent root and vector.

(d) AITK - program to square the current data matrix, so as to increase the speed of convergence in the process of extracting the latent root.

2. Form of data tape - The data tape should consist of the matrix of correlation coefficients or of corrected sums of squares and products. The program requires the complete matrix, including the principal diagonal.

OPERATING INSTRUCTIONS

Operation of this suite of programs is simplified if all of the programs are compiled onto the disk before the data are read, i.e.

> ·FORT *OUT-S:SMOD * *IN-R: *↑ *.FORT *OUT-S:EIG1 * *IN-R: *↑

```
* .FORT

* OUT-S:EIG2

*

*IN-R:

* ↑

* .FORT

* OUT-S:AITK

*

* IN-R:

* ↑
```

The data tape should now be placed in the high-speed reader, and read onto the disk as follows:

```
.FOSL
*IN-S:SMOD
*
*OPT-S:
*OUT-S:DATA
*IN-
* T
*READY
T
```

The program will pause for the entry of the number of variables, i. e. the dimension of the matrix, and this should be entered on the teletype and terminated by "Return." The program will type ' on completion.

The first latent root and vector can now be computed, as follows:

```
.FOSL
*IN-S:EIG1
*
*OPT-S:
*OUT-
*IN-S:DATA
*↑
*READY
↑
```

The program will pause for the entry of the dimension of the matrix, and this should be entered on the teletype and terminated by "Return." The high-speed punch should also be switched on as soon as this has been done. The program will output a vector on the high-speed punch and then type ' on completion. The speed of convergence of the computation depends partly on the dimension of the matrix and partly on the closeness of the latent roots. If the calculation does not end after five minutes or so, it is advisable to restart the computation after squaring the matrix (see operating instructions for the AITK program).

2

The latent root and vector can be printed, and extracted from the data matrix, as follows:

.FOSL *IN-S:EIG2 * *OPT-S: *OUT-S:DATA *IN-S:DATA *IN-S:DATA *T Output from EIG1 in high-speed *READY T

The program will pause for the entry of the dimension of the matrix, and this should be entered on the teletype and terminated by "Return." The program will print the eigenvalue and the eigenvector, and then store the residual data matrix on the disk, typing ' on completion. If further latent roots and vectors are required, return to program EIG1 above.

Convergence of the iterative procedure used in calculating the latent root and vector may, in certain cases, be slow. In these cases, the data matrix can be modified to improve the convergence as follows:

.FOSL *IN-S:AITK * *OPT-S: *OUT-S:DATA *IN-S:DATA * T *READY T

•

The program will pause for the entry of the dimension of the matrix, and this should be entered on the teletype, and terminated by "Return." This procedure can be repeated three or four times. In general, the speed of convergence will be increased by a factor of 2 for every time the procedure is used, but it is not advisable to apply the procedure too often because of possible loss of accuracy.

In difficult cases, convergence may not be reached even by applying the Aitken process. In such cases, the condition for convergence may be relaxed by altering the FORTRAN statement following the labelled statement 9 to:

IF (TEST-0.001) 6,6,7

OUTPUT

The only printed output is obtained from the EIG2 program, and consists of the eigenvalue and the associated eigenvector.

STORAGE

Normal for FORTRAN-D For the 4K version, the dimension of the matrix is limited to 12. METHOD

*

See "A Short Course In Multivariate Analysis," M. G. Kendall, Griffin, 1956.

SMOD

4

L C PROGRAM TO STORE MATRIX ON DISK DEFINE DISK DIMENSION R(144) ACCEPT 100, N N=N*N DO11=1, N READ 2, 101, R(I) CONTINUE 1 DO 2 1=1, N WRITE 3, 1Ø1, R(I) CONTINUE 2 100 FORMAT (I) FORMAT (/, E) 1Ø1 END

L	
С	PROGRAM TO COMPLITE LATENT POOT AND VECTOR
	DEFINE DISK
	TVDE 100
100	
dia(1)	FORMAT (/, "ENTER NO OF VARIABLES", /, /)
2.42	ACCEPT 101, N
101	FORMAT (I)
	NN=N*N
	DO 1 I=1, NN
	READ 3, 102, R(I)
1	CONTINUE
1ø2	FORMAT (/, E)
	DO 2 I=1, N
	$A(I) = \emptyset, \emptyset$
	K = I + N * (I - 1)
	$\Delta(1) = \Delta(1) \pm \mathcal{D}(K)$
2	
2	
2	
3.	CONTINUE
/	1ES1=10.10
	K=I
	DO 4 I=1, N
	$B(I)=\emptyset.\emptyset$
4	CONTINUE
	DO 5 I=1, N
	DO 5 J=1, N
	B(J)=B(J) + R(K) * A(I)
	K=K+1
5	CONTINUE
	V=B(1)
	B(I)=B(I)/V
	$TFST=TFST+\Delta RSF(\Lambda(I)-R(I))$
	$\Delta(I) = B(I)$
9	CONTINUE
	$IE (TEST_0 ddd) 4 4 7$
6	
0	
0	
0	CONTINUE
	END

*

C	PROGRAM TO PRINT LATENT ROOT AND VECTOR DEFINE DISK DIMENSION R(144), A(12)	
1,ØØ	ACCEPT 100, N FORMAT (I) DO 1 I=1, N READ 2, 101, A(I)	
1 1ø1	CONTINUE FORMAT (/, E) NN=N*N DO 2 I=1, NN READ 3, 1Ø1, R(I)	
2	CONTINUE ROOT= \emptyset . \emptyset DO 3 I=1, N ROOT=ROOT+A(I)*A(I)	
3	CONTINUE ROOT=1. \emptyset /SQTF(ROOT) EIG= \emptyset . \emptyset DO 4 I=1, N	
4	EIG=EIG+A(I)*R(I) CONTINUE TYPE 1Ø1,EIG DO 5 I=1, N	
5	A(I)=ROOT*A(I) TYPE 1Ø1, A(I) CONTINUE DO 6 I=1, N DO 6 J=1, N	
6	K=I+N^(J-T) R(K)=R(K)-A(I)*A(J)*EIG CONTINUE DO 7 I=1, NN WRITE 3, 1Ø1, R(I)	
7	CONTINUE END	

6

- 1	- 11	
- Change	- 1	-

1ø 1ø1

*

L?	
C	PROGRAM TO SQUARE MATRIX
	DEFINE DISK
	DIMENSION R(144)
	ACCEPT 100, N
1,ØØ	FORMAT (I)
	NN=N*N
	DO 1 1=1, NN
	READ 3, 1Ø1, R(1)
1	CONTINUE
	IR=Ø
	IK=-N
	DO 10 K=1, N
	IK=IK+N
	DO 10 J=1, N
	IR=IR+1
	JI=J-N
	IB=IK
	RNEW=Ø.Ø
	DO 20 1=1, N
	JI=JI+N
	IB=IB+1
	RNEW=RNEW+R(JI)*R(IB)
20	CONTINUE

RNEW=RNEW+R(JI)*
CONTINUE
WRITE 3, 101, RNEW
CONTINUE
FORMAT (E)
ENID

